# Evolution reaction-diffusion systems with positivity and mass control: <br> Global existence, Singular perturbations, $L^{\infty}, L^{p}, L^{1}, L^{2}$ approaches 

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## Goals of the talk:

- (1) To understand global existence in time for reaction-diffusion systems which have two main properties:
- positivity of the solutions is preserved
- the total mass of the solution is controlled
( $\Rightarrow L^{1}$ a priori estimate uniform in time)


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- This will exploit these $L^{1}$ estimates, but will also rely on $L^{p}$ and $L^{2}$ estimates
- (2) To apply the same $L^{2}$-estimates to the description of fast-reaction limits in some chemical systems and to existence questions for some cross-diffusion systems.


## An easy O.D.E.

$$
\left\{\begin{array}{l}
u^{\prime}=-u v^{\beta}, \\
v^{\prime}=u v^{\beta} \\
u(0)=u_{0} \geq 0, v(0)=v_{0} \geq 0, \\
u_{0}, v_{0} \text { given in }[0, \infty),
\end{array}\right.
$$

where $u, v:[0, T) \rightarrow \boldsymbol{R}$ are the unknown functions. Here $\beta \geq 1$. Local existence of a nonnegative unique solution on a maximal interval $\left[0, T^{*}\right)$ is well-known due to the $C^{1}$-property of $(u, v) \rightarrow u v^{\beta}$. Moreover $u \geq 0, v \geq 0$ and

$$
(u+v)^{\prime}(t)=0 \Rightarrow(u+v)(t)=u_{0}+v_{0}
$$

so that: $\sup _{t \in\left[0, T^{*}\right)}|u(t)|+|v(t)|<+\infty$,
and therefore

$$
T^{*}=+\infty
$$

What happens when diffusion is added?

$$
\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=-u v^{\beta} \text { in } Q_{T}=(0, T) \times \Omega \\
\partial_{t} v-d_{2} \Delta v=u v^{\beta} \text { in } Q_{T}=(0, T) \times \Omega \\
\partial_{\nu} u=\partial_{\nu} v=0 \text { on } \Sigma_{T}=(0, T) \times \partial \Omega, \\
u(0)=u_{0} \geq 0, \quad v(0)=v_{0} \geq 0 .
\end{array}\right.
$$

Here $\Omega \subset \boldsymbol{R}^{N}$, regular. The total mass is preserved:

$$
\begin{gathered}
\int_{\Omega} \partial_{t}(u+v)-\int_{\Omega} \Delta\left(d_{1} u+d_{2} v\right)=0 . \\
\partial_{\nu}\left(d_{1} u+d_{2} v\right)=0 \text { on } \partial \Omega \Rightarrow \int_{\Omega} \Delta\left(d_{1} u+d_{2} v\right)=0 . \\
\int_{\Omega}(u+v)(t)=\int_{\Omega} u_{0}+v_{0}
\end{gathered}
$$

Insufficient for global existence!

## Local existence for reaction－diffusion systems with $L^{\infty}$－data

$$
(S)\left\{\begin{array}{l}
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$$

－Theorem（ $L^{\infty}$－approach）：Let $u_{0}, v_{0} \in L^{\infty}(\Omega)$ ，
$u_{0} \geq 0, v_{0} \geq 0$ ．Then，there exist a maximum time $T^{*}>0$ and $(u, v)$ unique classical nonnegative solution of $(\mathrm{S})$ on ［ $0, T^{*}$［．Moreover，

$$
\sup _{t \in\left[0, T^{*}[ \right.}\left\{\|u(t)\|_{L^{\infty}(\Omega)}+\|v(t)\|_{L^{\infty}(\Omega)}\right\}<+\infty \Rightarrow\left[T^{*}+\infty\right]
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- Theorem ( $L^{\infty}$-approach): Let $u_{0}, v_{0} \in L^{\infty}(\Omega)$, $u_{0} \geq 0, v_{0} \geq 0$. Then, there exist a maximum time $T^{*}>0$ and $(u, v)$ unique classical nonnegative solution of $(\mathrm{S})$ on [ $0, T^{*}$. Moreover,

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- By maximum principle: $\|u(t)\|_{L^{\infty}(\Omega)} \leq\left\|u_{0}\right\|_{L^{\infty}(\Omega)}$. But, what about $v(t)$ ?

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$$

- By maximum principle: $\|u(t)\|_{L^{\infty}(\Omega)} \leq\left\|u_{0}\right\|_{L^{\infty}(\Omega)}$. But, what about $v(t)$ ?
- If $d_{1}=d_{2}: \partial_{t}(u+v)-d_{1} \Delta(u+v)=0$,

$$
\Rightarrow\|u(t)+v(t)\|_{L^{\infty}(\Omega)} \leq\left\|u_{0}+v_{0}\right\|_{L^{\infty}(\Omega)}
$$

$$
\Rightarrow T^{*}=+\infty!
$$

## Local existence for reaction-diffusion systems with $L^{\infty}$-data

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$$

What if $d_{1} \neq d_{2}$ ?
Remark: here $\int_{\Omega}(u+v)(t)=\int_{\Omega} u_{0}+v_{0}$, that is

$$
\sup _{t \in\left[0, T^{*}[ \right.}\left\{\|u(t)\|_{L^{1}(\Omega)},\|v(t)\|_{L^{1}(\Omega)}\right\} \leq\left\|u_{0}\right\|_{L^{1}(\Omega)}+\left\|v_{0}\right\|_{L^{1}(\Omega)} .
$$

How does this estimate help for global existence? Very frequent situation in applications !

## Same question for the general family of systems:

$$
\begin{cases}\forall i=1, \ldots, m & \\ \partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}\left(u_{1}, u_{2}, \ldots, u_{m}\right) & \text { in } Q_{T} \\ \partial_{\nu} u_{i}=0 & \text { on } \Sigma_{T} \\ u_{i}(0, \cdot)=u_{i}^{0}(\cdot) \geq 0 . & \end{cases}
$$

$d_{i}>0, f_{i}:[0, \infty)^{m} \rightarrow \boldsymbol{R}$ of class $C^{1}$ where

- (P): Positivity (nonnegativity) is preserved


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- (P): Positivity (nonnegativity) is preserved
-(M): $\sum_{1 \leq i \leq m} f_{i} \leq 0$ or more generally
- (M') $\forall r \in\left[0, \infty\left[{ }^{m}, \sum_{1 \leq i \leq m} a_{i} f_{i}(r) \leq C\left[1+\sum_{1 \leq i \leq m} r_{i}\right]\right.\right.$ for some $a_{i}>0$

$$
(E) \begin{cases}\forall i=1, \ldots, m & \\ \partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}\left(u_{1}, u_{2}, \ldots, u_{m}\right) & \text { in } Q_{T} \\ \partial_{\nu} u_{i}=0 & \text { on } \Sigma_{T} \\ u_{i}(0, \cdot)=u_{i}^{0}(\cdot) \geq 0 . & \end{cases}
$$

- (P) Preservation of Positivity (quasipositivity): $\forall i=1, \ldots, m$ $\forall r=\left(r_{1}, \ldots, r_{m}\right) \in\left[0, \infty\left[{ }^{m}, f_{i}\left(r_{1}, \ldots, r_{i-1}, 0, r_{i+1}, \ldots, r_{m}\right) \geq 0\right.\right.$.


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- (P) Preservation of Positivity $\forall i=1, \ldots, m$ $\forall r \in\left[0,+\infty\left[{ }^{m}, \quad f_{i}\left(r_{1}, \ldots, r_{i-1}, 0, r_{i+1}, \ldots, r_{m}\right) \geq 0\right.\right.$.
- (M): $\sum_{1 \leq i \leq m} f_{i}\left(r_{1}, \ldots, r_{m}\right) \leq 0 \Rightarrow$ 'Control of the Total Mass':

$$
\forall t \geq 0, \quad \int_{\Omega} \sum_{1 \leq i \leq r} u_{i}(t, x) d x \leq \int_{\Omega} \sum_{1 \leq i \leq r} u_{i}^{0}(x) d x
$$

Add up, integrate on $\Omega$, use $\int_{\Omega} \Delta u_{i}=\int_{\partial \Omega} \partial_{\nu} u_{i}=0$ :

$$
\int_{\Omega} \partial_{t}\left[\sum u_{i}(t)\right] d x=\int_{\Omega} \sum_{i} f_{i}(u) d x \leq 0 .
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- $\Rightarrow L^{1}(\Omega)$ - a priori estimates, uniform in time $\left(t \in\left[0, T^{*}\right)\right)$.

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- $\Rightarrow L^{1}(\Omega)$ - a priori estimates, uniform in time $\left(t \in\left[0, T^{*}\right)\right)$.
- Remark: same with (M')


## QUESTION: <br> What about Global Existence of solutions

## under assumption $(\mathbf{P})+(\mathrm{M}) ? ?$

or more generally (P)+(M') ??

Remarks: Global existence holds for the associated ODE. Global existence holds for the full system if all the $d_{i}$ are equal since then, by maximum principle
$\left\|\sum_{i} u_{i}(t)\right\|_{L^{\infty}(\Omega)} \leq\left\|\sum_{i} u_{i}(0)\right\|_{L^{\infty}(\Omega)}$.

## Explicit examples with property $(\mathbf{P})+(\mathrm{M})$ or $\left(\mathrm{M}^{\prime}\right)$

"Chemical morphogenetic process ("Brusselator", R.
Lefever-I. Prigogine-G. Nicolis)

$$
\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=-u v^{2}+b v \\
\partial_{t} v-d_{2} \Delta v=u v^{2}-(b+1) v+a \\
u_{\mid \partial \Omega}=b / a, v_{\mid \partial \Omega}=a \\
a, b, d_{1}, d_{2}>0
\end{array}\right.
$$

## Explicit examples with property $(\mathbf{P})+\left(\mathbf{M}^{\prime}\right)$

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See also: Glycolosis model-Gray-Scott models

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See also: Glycolosis model-Gray-Scott models

- Exothermic combustion in a gas

$$
\left\{\begin{aligned}
\partial_{t} Y-\mu \Delta Y & =-H(Y, T) \\
\partial_{t} T-\lambda \Delta T & =q H(Y, T)
\end{aligned}\right.
$$

$Y=$ concentration of a reactant, $T=$ temperature,

## Explicit examples with $(\mathbf{P})+\left(\mathrm{M}^{\prime}\right)$

- Lotka-Volterra Systems

$$
\forall i=1 \ldots m, \quad \partial_{t} u_{i}-d_{i} \Delta u_{i}=e_{i} u_{i}+u_{i} \sum_{1 \leq j \leq m} p_{i j} u_{j}
$$

with $e_{i}, p_{i j} \in \boldsymbol{R}$ such that for some $a_{i}>0$.

$$
\forall w \in[0, \infty)^{m}, \sum_{i, j=1}^{m} a_{i} w_{i} p_{i j} w_{j} \leq 0, \quad\left[\Rightarrow\left(\mathbf{M}^{\prime}\right)\right]
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$$

with $e_{i}, p_{i j} \in R$ such that for some $a_{i}>0$.

$$
\forall w \in[0, \infty)^{m}, \sum_{i, j=1}^{m} a_{i} w_{i} p_{i j} w_{j} \leq 0, \quad\left[\Rightarrow\left(\mathbf{M}^{\prime}\right)\right]
$$

- Diffusive epidemic models: SIR
$S=$ Susceptibles= can be infected
$I=$ Infectives $=$ infected and transmit disease
$R=$ Removed $=$ immune; $P=S+I+R$

$$
\left\{\begin{array}{l}
S_{t}-\nabla \cdot d_{1}(x) \nabla S=b P-(m+k P) S-g(S, I) \\
I_{t}-\nabla \cdot d_{2}(x) \nabla I=-(m+k P) I+g(S, I)-\lambda I \\
R_{t}-\nabla \cdot d_{3}(x) \nabla R=-(m+k P) R+\lambda I
\end{array}\right.
$$

May be coupled with an extra variable: $S=S(t, x$, age $) \ldots$

## Elementary chemical reactions: a simple example

$$
U_{1}+U_{2} \underset{\overrightarrow{k^{-}}}{\frac{k^{+}}{}} U_{3}
$$

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U_{1}+U_{2} \stackrel{k^{+}}{\stackrel{k^{-}}{-}} U_{3}
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- $u_{i}=$ concentration of $U_{i}$. Assume first $u_{i}=u_{i}(t)$ (independent of the spatial variable)


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－Law of Mass Action：In each reaction，the instantaneous variation of concentration of each $u_{i}$ is proportional to the concentration of the reactants：

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\frac{d}{d t} u_{1}=k^{-} u_{3}-k^{+} u_{1} u_{2}
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$$
\frac{d}{d t} u_{1}=k^{-} u_{3}-k^{+} u_{1} u_{2}
$$

- Whence the full system of O.D.E.:

$$
\begin{aligned}
& \frac{d}{d t} u_{1}=k^{-} u_{3}-k^{+} u_{1} u_{2} \\
& \frac{d}{d t} u_{2}=k^{-} u_{3}-k^{+} u_{1} u_{2} \\
& \frac{d}{d t} u_{3}=-k^{-} u_{3}+k^{+} u_{1} u_{2}
\end{aligned}
$$

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－Instantaneous variation of $u_{i}: \partial_{t} u_{i}+\nabla \cdot\left(u_{i} \mathbf{V}_{\mathbf{i}}\right)$ where $\mathbf{V}_{\mathbf{i}}=$ velocity of the particule $U_{i}$

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$$
\partial_{t} u_{1}+\nabla \cdot\left(u_{1} \mathbf{V}_{1}\right)=k^{-} u_{3}-k^{+} u_{1} u_{2}
$$

- Fick's diffusion law:

$$
\mathbf{u}_{1} \mathbf{V}_{1}=-d_{1} \nabla u_{1} \Rightarrow \nabla \cdot\left(u_{1} \mathbf{V}_{1}\right)=-d_{1} \Delta u_{1}
$$

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- Instantaneous variation of $u_{i}: \partial_{t} u_{i}+\nabla \cdot\left(u_{i} \mathbf{V}_{\mathbf{i}}\right)$ where $\mathbf{V}_{\mathbf{i}}=$ velocity of the particule $U_{i}$
- Law of Mass Action: it is proportional to the concentration of the reactants:

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- Fick's diffusion law:

$$
\mathbf{u}_{1} \mathbf{V}_{\mathbf{1}}=-d_{1} \nabla u_{1} \Rightarrow \nabla \cdot\left(u_{1} \mathbf{V}_{1}\right)=-d_{1} \Delta u_{1}
$$

$$
\left\{\begin{array}{l}
\partial_{t} u_{1}-d_{1} \Delta u_{1}=-k^{+} u_{1} u_{2}+k^{-} u_{3} \\
\partial_{t} u_{2}-d_{2} \Delta u_{2}=-k^{+} u_{1} u_{2}+k^{-} u_{3} \\
\partial_{t} u_{3}-d_{3} \Delta u_{3}=k^{+} u_{1} u_{2}-k^{-} u_{3}
\end{array}\right.
$$

Note : $f_{1}+f_{2}+2 f_{3}=0$ and positivity is preserved.

## A quadratic model

$$
U_{1}+U_{2} \stackrel{k^{+}}{\stackrel{k^{-}}{*}} U_{3}+U_{4}
$$

$$
\left\{\begin{aligned}
\partial_{t} u_{1}-d_{1} \Delta u_{1} & =-k^{+} u_{1} u_{2}+k^{-} u_{3} u_{4} \\
\partial_{t} u_{2}-d_{2} \Delta u_{2} & =-k^{+} u_{1} u_{2}+k^{-} u_{3} u_{4} \\
\partial_{t} u_{3}-d_{3} \Delta u_{3} & =k^{+} u_{1} u_{2}-k^{-} u_{3} u_{4} \\
\partial_{t} u_{4}-d_{4} \Delta u_{4} & =k^{+} u_{1} u_{2}-k^{-} u_{3} u_{4}
\end{aligned}\right.
$$

Note: $f_{1}+f_{2}+f_{3}+f_{4}=0$ and positivity is preserved.

## Superquadratic reaction-diffusion systems.

- A general chemical reaction:

$$
p_{1} U_{1}+p_{2} U_{2}+\ldots+p_{m} U_{m} \stackrel{k^{+}}{\stackrel{\rightharpoonup}{k^{-}}} q_{1} U_{1}+q_{2} U_{2}+\ldots+q_{m} U_{m}
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- Global existence in general ?


## Models in electromigration (Nernst-Planck)

$$
\left\{\begin{array}{l}
\partial_{t} c_{i}-d_{i} \operatorname{div}\left(\nabla c_{i}+z_{i} c_{i} \nabla \Phi\right)=f_{i}(c) \text { in } Q \\
-\Delta \Phi=\sum_{i=1}^{m} z_{i} c_{i} \text { in } Q \\
+ \text { initial and boundary conditions. }
\end{array}\right.
$$

$c_{i}=c_{i}(t, x)=$ concentration of ionized species
with charge number $z_{i} \in \boldsymbol{R}$
$\Phi$ is the electrical potential
The nonlinearity $f_{i}$ have the same structure (reversible chemical reactions).
see Amann-Renardy, Gajewski-Glitzsky-Gröger-Hünlich, Choi-Lui, Biler-Dolbeault, Hebisch-Nadzieja, Bothe-Fischer-Saal, Bothe-Fischer-P.-Rolland,...

## Models with degenerate diffusion

- Modelization of pollutants transfer in atmospher ( $N=3$ ): W. Fitzgibbon-M. Langlais-J. Morgan,R. Texier-PicardMP:

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\left\{\begin{array}{l}
\partial_{t} \phi_{i}=d_{i} \partial_{z z}^{2} \phi_{i}+\omega \cdot \nabla \phi_{i}+f_{i}(\phi)+g_{i}, \forall i=1 \ldots 20, \\
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- The reaction terms:

$$
\begin{aligned}
& \int f_{1}(\phi)=-k_{1} \phi_{1}+k_{22} \phi_{19}+k_{25} \phi_{20}+k_{11} \phi_{13}+k_{9} \phi_{11} \phi_{2}+k_{3} \phi_{5} \phi_{2} \\
& +k_{2} \phi_{2} \phi_{4}-k_{23} \phi_{1} \phi_{4}-k_{14} \phi_{1} \phi_{6}+k_{12} \phi_{10} \phi_{2}-k_{10} \phi_{11} \phi_{1}-k_{24} \phi_{19} \phi_{1} \text {, } \\
& f_{2}(\phi)=k_{1} \phi_{1}+k_{21} \phi_{19}-k_{9} \phi_{11} \phi_{2}-k_{3} \phi_{5} \phi_{2}-k_{2} \phi_{2} \phi_{4}-k_{12} \phi_{10} \phi_{2} \\
& f_{3}(\phi)=k_{1} \phi_{1}+k_{17} \phi_{4}+k_{19} \phi_{16}+k_{22} \phi_{19}-k_{15} \phi_{3} \\
& f_{4}(\phi)=-k_{17} \phi_{4}+k_{15} \phi_{3}-k_{16} \phi_{4}-k_{2} \phi_{2} \phi_{4}-k_{23} \phi_{1} \phi_{4} \\
& f_{5}(\phi)=2 k_{4} \phi_{7}+k_{7} \phi_{9}+k_{13} \phi_{14}+k_{6} \phi_{7} \phi_{6}-k_{3} \phi_{5} \phi_{2}+k_{20} \phi_{17} \phi_{6} \\
& f_{6}(\phi)=2 k_{18} \phi_{16}-k_{8} \phi_{9} \phi_{6}-k_{6} \phi_{7} \phi_{6}+k_{3} \phi_{5} \phi_{2}-k_{20} \phi_{17} \phi_{6}-k_{14} \phi_{1} \phi_{6} \\
& f_{7}(\phi)=-k_{4} \phi_{7}-k_{5} \phi_{7}+k_{13} \phi_{14}-k_{6} \phi_{7} \phi_{6} \\
& f_{8}(\phi)=k_{4} \phi_{7}+k_{5} \phi_{7}+k_{7} \phi_{9}+k_{6} \phi_{7} \phi_{6} \\
& f_{9}(\phi)=-k_{7} \phi_{9}-k_{8} \phi_{9} \phi_{6} \\
& f_{10}(\phi)=k_{7} \phi_{9}+k_{9} \phi_{11} \phi_{2}-k_{12} \phi_{10} \phi_{2} \\
& f_{11}(\phi)=k_{11} \phi_{13}-k_{9} \phi_{11} \phi_{2}+k_{8} \phi_{9} \phi_{6}-k_{10} \phi_{11} \phi_{1} \\
& f_{12}(\phi)=k_{9} \phi_{11} \phi_{2} \\
& f_{13}(\phi)=-k_{11} \phi_{13}+k_{10} \phi_{11} \phi_{1} \\
& f_{14}(\phi)=-k_{13} \phi_{14}+k_{12} \phi_{10} \phi_{2} \\
& f_{15}(\phi)=k_{14} \phi_{1} \phi_{6} \\
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& f_{17}(\phi)=-k_{20} \phi_{17} \phi_{6} \\
& f_{18}(\phi)=k_{20} \phi_{17} \phi_{6} \\
& f_{19}(\phi)=-k_{21} \phi_{19}-k_{22} \phi_{19}+k_{25} \phi_{20}+k_{23} \phi_{1} \phi_{4}-k_{24} \phi_{19} \phi_{1} \\
& f_{20}(\phi)=-k_{25} \phi_{20}+k_{24} \phi_{19} \phi_{1} \text {. }
\end{aligned}
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Back to the model example: what about $L^{\infty}$-estimates?

$$
(S)\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=-u v^{\beta} \text { on } Q_{T} \\
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\partial_{\nu} u=\partial_{\nu} v=0 \text { on } \Sigma_{T} \\
u(0)=u_{0} \geq 0, \quad v(0)=v_{0} \geq 0
\end{array}\right.
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By maximum principle

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\partial_{t} u-d_{1} \Delta u \leq 0 \Rightarrow\|u(t)\|_{L^{\infty}(\Omega)} \leq\left\|u_{0}\right\|_{L^{\infty}(\Omega)}
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- If $d_{1}=d_{2}=d: \partial_{t}(u+v)-d \Delta(u+v)=0$

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\begin{gathered}
\Rightarrow\|u(t)+v(t)\|_{L^{\infty}(\Omega)} \leq\left\|u_{0}+v_{0}\right\|_{L^{\infty}(\Omega)} \\
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- What happens when $d_{1} \neq d_{2}$ ?


## A general $L^{p}$-approach

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\partial_{t} v-d_{2} \Delta v=-\left[\partial_{t} u-d_{1} \Delta u\right], u \in L^{\infty}\left(Q_{T^{*}}\right)
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FORMALLY : $v=-\left[\partial_{t}-d_{2} \Delta\right]^{-1}\left(\partial_{t}-d_{1} \Delta\right) u(=\mathcal{A} u)$.

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－Lemma：the operator $\mathcal{A}$ is continuous from $L^{p}\left(Q_{T}\right)$ into $L^{p}\left(Q_{T}\right)$ for all $\left.p \in\right] 1, \infty[$ and all $T>0$ ．

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\Rightarrow \forall p<+\infty,\|v\|_{L^{p}\left(Q_{T^{*}}\right)}<+\infty
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- Next

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- Therefore

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\|v\|_{L^{\infty}\left(Q_{T^{*}}\right)}<+\infty \text { and } T^{*}=+\infty .
$$

## The proof of the $L^{p}$-estimate by duality

$$
\partial_{t} v-d_{2} \Delta v \leq-\left[\partial_{t} u-d_{1} \Delta u\right], \quad v \geq 0,
$$

implies the existence of $C=C\left(p, T, \Omega, u_{0}, v_{0}\right)$ such that:

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\left\{\begin{array}{l}
-\left(\partial_{t} \psi+d_{2} \Delta \psi\right)=\Theta \in C_{0}^{\infty}\left(Q_{T}\right), \Theta \geq 0, \\
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$\Rightarrow \Rightarrow\left|\int_{Q_{T}} v \Theta\right| \leq C\|\Theta\|_{L^{p^{\prime}}\left(Q_{T}\right)} \Rightarrow L^{p}\left(Q_{T}\right)$-estimate on $v$ by duality.

## Extensions and limits of the $L^{p}$－approach

－The same approach provides global existence
－for the＂Brusselator＂，for the epidemic models SIR
－for the $3 \times 3$ system

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U_{1}+U_{2} \stackrel{k^{+}}{\overrightarrow{k^{-}}} U_{3}:\left\{\begin{array}{l}
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- More generally it applies to $m \times m$ systems if there exists a triangular invertible matrix $Q$ with nonnegative entries such that

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\forall r \in[0, \infty)^{m}, Q f(r) \leq\left[1+\sum_{1 \leq i \leq m} r_{i}\right] \mathbf{b}
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- Can be used for general systems with only (P)+(M) when the $d_{i}$ are close to each other.


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- Blow up in finite time may occur near the boundary in the system [Bebernes-Lacey]

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\end{array}\right.
$$

## Extensions and limits of the $L^{p}$-approach

- All the previous results extends to Dirichlet or Robin type boundary conditions, assuming they are all of the same type in all equations or when they "combine well enough"
- Blow up in finite time may occur near the boundary in the system [Bebernes-Lacey]

$$
\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=-u v^{\beta} \text { in } Q_{T} \\
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\end{array}\right.
$$

- Extends to Wentzell type boundary conditions, like

$$
\left\{\begin{array}{l}
\partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}(u) \text { in } Q_{T} \\
\sigma \partial_{t} u_{i}+d_{i} \partial_{\nu} u_{i}-\delta_{i} \Delta_{\partial \Omega} u_{i}=g_{i}(u) \text { on } \Sigma_{T}
\end{array}\right.
$$

with $\sigma, \delta_{i} \geq 0$ and " good $g_{i}$ 's. [G. Goldstein, J. Goldstein, M. Meyries, M.P.]

## Extensions and limits of the $L^{p}$-approach

- $L^{p}$-approach is not enough for global existence in

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\partial_{t} u-d_{1} \Delta u=-u h(v) \text { in } Q_{T} \\
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when $h(v)$ grows faster than a polynomial.

## Extensions and limits of the $L^{p}$-approach

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\left\{\begin{aligned}
\partial_{t} u-d_{1} \Delta u & =-u h(v) \text { in } Q_{T} \\
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\end{aligned}\right.
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when $h(v)$ grows faster than a polynomial.

- The case $h(v)=e^{v}$ can be reached for this particular system by using Orlicz spaces, rather than $L^{p}$. There is also a different method based on the use of a specific Lyapunov function which works with systems with more specific stucture \{K. Masuda, J.I. Kanel, A. Haraux, A. Youkana, A. Barabanova, M. Kirane, S. Kouachi, S. Benachour, B. Rebiai,...\}


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Barabanova, M. Kirane, S. Kouachi, S. Benachour, B. Rebiai,...\}
- Still the system

$$
\left\{\begin{aligned}
\partial_{t} u-d_{1} \Delta u & =-u e^{v^{2}} \text { in } Q_{T} \\
\partial_{t} v-d_{2} \Delta v & =u e^{v^{2}} \text { in } Q_{T}
\end{aligned}\right.
$$

remains open.

## Extensions and limits of the $L^{p}$-approach

- $L^{p}$-approach does not apply to

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\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=u^{3} v^{2}-u^{2} v^{3} \text { in } Q_{T} \\
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－and even not to the＂better＂system with $\lambda \in[0,1[$

$$
\left\{\begin{array}{c}
\partial_{t} u-d_{1} \Delta u=\lambda u^{3} v^{2}-u^{2} v^{3} \text { in } Q_{T}, \\
\partial_{t} v-d_{2} \Delta v=u^{2} v^{3}-u^{3} v^{2} \text { in } Q_{T}
\end{array}\right.
$$

where $f(u, v)+g(u, v) \leq 0$ and also $f(u, v)+\lambda g(u, v) \leq 0$

## Finite time $L^{\infty}$-blow up may appear!

$$
\left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=f(u, v) \text { in } Q_{T} \\
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\end{array}\right.
$$

Theorem: (D. Schmitt, MP) One can find polynomial nonlinearities $f, g$ satisfying ( $\mathbf{P}$ ) and

$$
\text { (M) } f+g \leq 0, \text { and also : } \exists \lambda \in[0,1[, f+\lambda g \leq 0,
$$

and for which there exists $T^{*}<+\infty$ with

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\lim _{t \rightarrow T^{*}}\|u(t)\|_{L^{\infty}(\Omega)}=+\infty=\lim _{t \rightarrow T^{*}}\|v(t)\|_{L^{\infty}(\Omega)}
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- The blow up is similar to $u(t, x)=\frac{1}{\left(T^{*}-t\right)^{2}+|x|^{2}}$ which is solution of $\partial_{t} u-\Delta u=g(t, x) u^{2}$ with $g \in L^{\infty}, N \geq 4$. The solution goes out of $L^{\infty}(\Omega)$ at $t=T^{*}$, but still exists for $t>T^{*} .--->$ Incomplete blow up!


## Idea of the proof of the＂possible blow up＂Theorem

－Look for solutions of the form

$$
u(t, x)=\frac{a\left(T^{*}-t\right)+b|x|^{2}}{\left[T^{*}-t+|x|^{2}\right]^{\gamma}}, \quad v(t, x)=\frac{c\left(T^{*}-t\right)+d|x|^{2}}{\left[T^{*}-t+|x|^{2}\right]^{\gamma}},
$$

Find $a, b, c, d, d_{1}, d_{2}>0, \gamma>1, N \geq 1$ so that $u, v$ be solutions of a $\mathbf{( P ) + ( M ) ~ s y s t e m . ~}$

## Idea of the proof of the "possible blow up" Theorem

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- There are examples even in dimension $N=1$.


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- There are examples even in dimension $N=1$.
- By choosing $N$ large enough, we can obtain blow up with nonlinearities $f(u, v), g(u, v)$ with growth $2+\epsilon, \epsilon>0$ as small as we want.


## CONCLUSION at this stage:

Look rather for weak solutions which are allowed to go out of $L^{\infty}(\Omega)$ from time to time or even often.

We ask the nonlinearities to be at least in $L^{1}\left(Q_{T}\right)$.

$$
f_{i}(u) \in L^{1}\left(Q_{T}\right) ?
$$

## An $L^{1}$-approach

$$
(S) \begin{cases}\forall i=1, \ldots, m & \\ \partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}\left(u_{1}, u_{2}, \ldots, u_{m}\right) & \text { in } Q_{T} \\ \partial_{\nu} u_{i}=0 & \text { on } \Sigma_{T} \\ u_{i}(0, \cdot)=u_{i}^{0}(\cdot) \geq 0 . & \end{cases}
$$

- $L^{1}$-Theorem. Assume the two conditions ( $\mathbf{P}$ )+( $\mathbf{M}^{\prime}$ ) hold. Assume moreover that the following a priori estimate holds:

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\forall i=1, \ldots, m, \int_{Q_{T}}\left|f_{i}(u)\right| \leq C
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Assume $u_{i}^{0} \in L^{1}(\Omega)$. Then, there exists a global weak solution for System (S).

- Proof: via supersolutions and truncations techniques !


## Main ingredients in the proof of the $L^{1}$-theorem

- Truncating the $f_{i} \rightarrow f_{i}^{n}, u_{i}^{0} \rightarrow\left(u_{i}^{0}\right)^{n} \mapsto$ global approximate solutions $u_{i}^{n}$ with $\left\|f_{i}^{n}\left(u^{n}\right)\right\|_{L^{1}\left(Q_{T}\right)}$ bounded independently of $n$

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$$

- Compactness of the mapping $\left(g, w_{0}\right) \in L^{1}\left(Q_{T}\right) \times L^{1}(\Omega) \mapsto w \in L^{1}\left(Q_{T}\right)$ where

$$
\partial_{t} w-d \Delta w=g \text { on } Q_{T}, w(0, \cdot)=w_{0}, \partial_{\nu} w=0 \text { on } \partial \Omega .
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so that $u_{i}^{n} \rightarrow u_{i}$ in $L^{1}\left(Q_{T}\right)$ and a.e. as $n \rightarrow+\infty$

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so that $u_{i}^{n} \rightarrow u_{i}$ in $L^{1}\left(Q_{T}\right)$ and a.e. as $n \rightarrow+\infty$

- We first prove that the limit $u_{i}$ is a supersolution.
- For this, we use the equation satisfied by

$$
T_{k}\left(u_{i}^{n}+\eta \sum_{j \neq i} u_{j}^{n}\right) \text { where } T_{k}(r)=\min \{r, k\}, \eta>0
$$

## Main ingredients in the proof of the $L^{1}$-theorem

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u_{i}^{n}(0, \cdot)=u_{i}^{0} \geq 0,
\end{array} \quad \sup _{i}\left\|f_{i}^{n}\left(u^{n}\right)\right\|_{L^{1}\left(Q_{T}\right)} \leq C(T) \text { for all } T>0 .(*)\right. \text {. }
$$

- If $m=1: \partial_{t} T_{k}\left(u_{1}^{n}\right)-d_{1} \Delta T_{k}\left(u_{1}^{n}\right) \geq T_{k}^{\prime}\left(u_{1}^{n}\right) f_{1}^{n}\left(u_{1}^{n}\right)$.

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- The limit $u_{i}$ is a supersolution by letting successively: $n \rightarrow \infty, \eta \rightarrow 0, k \rightarrow+\infty$.

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- Main estimate for $\eta \rightarrow 0: \int_{\left[u_{i}^{n} \leq k\right]}\left|\nabla u_{i}^{n}\right|^{2} \leq C k$


## End of the proof of the $L^{1}$-theorem

- Since $u_{i}$ is a supersolution, we have

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\partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}(u)+\mu_{i}, \quad 0 \leq \mu_{i}(=\text { nonnegative measure }) .
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－By（M）：

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\partial_{t}\left(\sum_{i} u_{i}^{n}\right)-\Delta\left(\sum_{i} d_{i} u_{i}^{n}\right)=\sum_{i} f_{i}^{n}\left(u^{n}\right) \leq 0
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## End of the proof of the $L^{1}$-theorem

- Since $u_{i}$ is a supersolution, we have

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\partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}(u)+\mu_{i}, \quad 0 \leq \mu_{i}(=\text { nonnegative measure }) .
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- By Fatou's lemma

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$$
\begin{aligned}
& \partial_{t}\left(\sum_{i} u_{i}\right)-\Delta\left(\sum_{i} d_{i} u_{i}\right) \leq \sum_{i} f_{i}(u), \\
& \sum_{i}\left[f_{i}(u)+\mu_{i}\right] \leq \sum_{i} f_{i}(u) \Rightarrow \mu_{i} \equiv 0 \forall i .
\end{aligned}
$$

## $L^{1}$-Theorem applies to many situations

$$
\begin{aligned}
& \left\{\begin{array}{l}
\partial_{t} u-d_{1} \Delta u=-u e^{v^{2}} \text { in } Q_{T} \\
\partial_{t} v-d_{2} \Delta v=u e^{v^{2}} \text { in } Q_{T}
\end{array}\right. \\
& \int_{\Omega} u(T)+\int_{Q_{T}} u e^{v^{2}}=\int_{\Omega} u_{0},
\end{aligned}
$$

whence the $L^{1}\left(Q_{T}\right)$-estimate of the nonlinearity.

## $L^{1}$-Theorem applies to many situations

$$
\left\{\begin{array}{c}
\partial_{t} u-d_{1} \Delta u=\lambda u^{3} v^{2}-u^{2} v^{3} \text { in } Q_{T}, \\
\partial_{t} v-d_{2} \Delta v=u^{2} v^{3}-u^{3} v^{2} \text { in } Q_{T}
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& \int_{\Omega} u(T)+\int_{Q_{T}} u^{2} v^{3}=\lambda \int_{Q_{T}} u^{3} v^{2}+\int_{\Omega} u_{0} . \\
& \quad \int_{\Omega} v(T)+\int_{Q_{T}} u^{3} v^{2}=\int_{Q_{T}} u^{2} v^{3}+\int_{\Omega} v_{0} u^{3} v^{2} \leq \lambda \int_{Q_{T}} u^{3} v^{2}+\int_{\Omega} u_{0}+v_{0}
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$$
\text { For } \lambda<1: \Rightarrow \int_{Q_{T}} u^{3} v^{2}<+\infty, \int_{Q_{T}} u^{2} v^{3}<+\infty
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- Open problem if $\lambda=1$ : $L^{1}$-estimate of the nonlinearity??


## $L^{1}$-Theorem applies to many situations

- More generally it applies if there exists an invertible matrix $Q$ with nonnegative entries such that

$$
\forall r \in[0, \infty)^{m}, Q f(r) \leq\left[1+\sum_{1 \leq i \leq m} r_{i}\right] \mathbf{b},
$$

for some $\mathbf{b} \in \boldsymbol{R}^{m}, f=\left(f_{1}, \ldots, f_{m}\right)^{t}$.
(In other words, there are $m$ linearly independent inequalities for the $f_{i}$ 's and not only one).

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(In other words, there are $m$ linearly independent inequalities for the $f_{i}$ 's and not only one).

- Extends partially to electro-diffusion-reaction systems.


## A surprising a priori $L^{2}$-estimate for these systems

$$
\text { (S) } \begin{cases}\forall i=1, \ldots, m & \\ \partial_{t} u_{i}-d_{i} \Delta u_{i}=f_{i}\left(u_{1}, u_{2}, \ldots, u_{m}\right) & \text { in } Q_{T} \\ \partial_{\nu} u_{i}=0 & \text { on } \Sigma_{T} \\ u_{i}(0, \cdot)=u_{i}^{0}(\cdot) \geq 0 . & \end{cases}
$$

$L^{2}$-Theorem. Assume ( $\mathbf{P} \mathbf{)}+\left(\mathbf{M}^{\prime}\right)$. Then, the following a priori estimate holds for the solutions of $(\mathrm{S})$ :

$$
\forall i=1, \ldots, m, \forall T>0, \quad \int_{Q_{T}} u_{i}^{2} \leq C\left[1+\sum_{i} \int_{\Omega}\left(u_{i}^{0}\right)^{2}\right] .
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- Corollary of the $L^{1}$ - and $L^{2}$-Theorems: Assume ( $\mathbf{P}$ ),( $\mathbf{M}^{\prime}$ ) and $f_{i}$ is at most quadratic. Then, System (S) has a global weak solution.


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- Corollary of the $L^{1}$ - and $L^{2}$-Theorems: Assume ( $\mathbf{P}$ ),( $\mathbf{M}^{\prime}$ ) and $f_{i}$ is at most quadratic. Then, System (S) has a global weak solution.
- Recall that nonlinearities are quadratic in many examples.


## Application to the quadratic chemical reaction:

$$
\begin{gathered}
U_{1}+U_{2} \stackrel{k^{+}}{\stackrel{k^{+}}{k^{-}}} U_{3}+U_{4} \\
\left\{\begin{array}{cc}
\partial_{t} u_{1}-d_{1} \Delta u_{1}= & -k^{+} u_{1} u_{2}+k^{-} u_{3} u_{4} \\
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U_{1}+U_{2} \frac{k^{+}}{\bar{k}} U_{3}+U_{4} \\
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\partial_{2} u_{1}-d_{1} \Delta u_{1}=-k^{+} u_{1} u_{2}+k^{-} u_{3} u_{4} \\
\partial_{2} u_{2}-d_{2} \Delta u_{2}=-k^{+} u_{1} u_{2}+k^{-} u_{3} u_{4} \\
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－Global existence of a weak solution

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- The $L^{p}$-approach does not work


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－This solution is regular（＝classical）in dimension $N=1,2$

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- Global existence of a weak solution
- The $L^{p}$-approach does not work
- This solution is regular (=classical) in dimension $N=1,2$
- For $N \geq 3$, the set of points around which the solution is unbounded is "small" in the sense that its Hausdorff dimension is at most $\left(N^{2}-4\right) / N$


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- Global existence of a weak solution
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- For $N \geq 3$, the set of points around which the solution is unbounded is "small" in the sense that its Hausdorff dimension is at most $\left(N^{2}-4\right) / N$
- Open problem: does the solution blow up in $L^{\infty}(\Omega)$ in finite time or not??


## Some references for the quadratic chemical reaction：

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-     - M.P. (L ${ }^{1}$-theorem: global weak solutions);
- L. Desvillettes, K. Fellner, M.P., J. Vovelle: different proof using entropy inequality and based on $(L \log L)^{2}$-estimates on $u_{i}$.
- Strong solutions for $N=1$ : L. Desvillettes, K. Fellner
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- estimate on the size of the "blow-up set" when $N \geq 3$ : Th.

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Goudon, A. Vasseur

- And also, strong solutions for (rather general) strongly subquadratic systems: J.I. Kanel-M. Caputo, A. Vasseur

Idea of the proof of the $L^{2}$-estimate

$$
\partial_{t}\left(\sum_{i} u_{i}\right)-\Delta\left(\sum_{i} d_{i} u_{i}\right) \leq 0
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\begin{gathered}
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\partial_{t} W-\Delta(A W) \leq 0, \quad W=\sum_{i} u_{i} A=\frac{\sum_{i} d_{i} u_{i}}{\sum_{i} u_{i}}
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- The operator $W \rightarrow \partial_{t} W-\Delta(A W)$ is not of divergence form and $A$ is not continuous, but bounded from above and from below so that the operator is parabolic and, at least:

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\|W\|_{L^{2}\left(Q_{T}\right)} \leq C\left\|W_{0}\right\|_{L^{2}(\Omega)}
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- We may even show that the mapping $W_{0} \in L^{2}(\Omega) \rightarrow W \in L^{2}\left(Q_{T}\right)$ is compact where $\partial_{t} W-\Delta(A W)=0, W(0)=W_{0}$.


## A proof of the linear $L^{2}$-estimate: by duality

Introduce the dual problem

$$
\left\{\begin{array}{l}
-\partial_{t} \psi-A \Delta \psi=\Theta \in C_{0}^{\infty}\left(Q_{T}\right)^{+}  \tag{1}\\
\psi(T)=0, \partial_{\nu} \psi=0 \text { on } \Sigma_{T}
\end{array}\right.
$$

Then, from $\partial_{t} W-\Delta(A W) \leq 0$, we deduce

$$
\int_{Q_{T}} W \Theta=\int_{\Omega} \psi(0) W_{0} \leq\|\psi(0)\|_{L^{2}(\Omega}\left\|W_{0}\right\|_{L^{2}(\Omega)}
$$

But multiplying (2) by $-\Delta \psi$ gives

$$
\begin{gathered}
\int_{Q_{T}} \Delta \psi \partial_{t} \psi+A(\Delta \psi)^{2}=-\int_{Q_{T}} \Theta \Delta \psi \\
\int_{Q_{T}} \Delta \psi \partial_{t} \psi=-\int_{Q_{T}} \nabla \psi \partial_{t} \nabla \psi=-\frac{1}{2} \int_{Q_{T}} \partial_{t}|\nabla \psi|^{2}=\frac{1}{2} \int_{\Omega}|\nabla \psi(0)|^{2} \geq 0
\end{gathered}
$$

## $L^{2}$-bound and even $L^{2}$-compactness !

$$
\left\{\begin{array}{l}
-\partial_{t} \psi-A \Delta \psi=\Theta \in C_{0}^{\infty}\left(Q_{T}\right)^{+}  \tag{2}\\
\psi(T)=0, \partial_{\nu} \psi=0 \text { on } \Sigma_{T}
\end{array}\right.
$$

We deduce, for various $C=C(\underline{d}, \bar{d}, T)$ :

$$
\begin{gathered}
\int_{Q_{T}}(\Delta \psi)^{2} \leq C \int_{Q_{T}} \Theta^{2}, \int_{Q_{T}}\left(\partial_{t} \psi\right)^{2} \leq C \int_{Q_{T}} \Theta^{2}, \\
\int_{\Omega}(\psi(0))^{2}+\int_{\Omega}|\nabla \psi(0)|^{2} \leq C \int_{Q_{T}} \Theta^{2} \\
\int_{Q_{T}} W \Theta=\int_{\Omega} W_{0} \psi(0) \leq C\left\|W_{0}\right\|_{L^{2}(\Omega)}\|\Theta\|_{L^{2}\left(Q_{T}\right)} . \\
\Rightarrow\|W\|_{L^{2}\left(Q_{T}\right)} \leq C\left\|W_{0}\right\|_{L^{2}(\Omega)} .
\end{gathered}
$$

Even better: $W_{0} \in L^{2}(\Omega) \rightarrow W \in L^{2}\left(Q_{T}\right)$ is compact ! since $\Theta \in L^{2}\left(Q_{T}\right) \rightarrow \psi(0) \in L^{2}(\Omega)$ is compact

## Three extensions of the $L^{2}$-estimate: (1)

- It extends to nonlinear diffusions of the form

$$
\partial_{t} u_{i}-\nabla \cdot\left(d_{i}\left(u_{i}\right) \nabla u_{i}\right)=f_{i}(u), \underline{d} \leq d_{i} \leq \bar{d} .
$$

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- It extends to nonlinear diffusions of the form

$$
\partial_{t} u_{i}-\nabla \cdot\left(d_{i}\left(u_{i}\right) \nabla u_{i}\right)=f_{i}(u), \underline{d} \leq d_{i} \leq \bar{d} .
$$

- if $D_{i}(r)=\int_{0}^{r} d_{i}(s) d s$, Condition (M) implies

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\partial_{t}\left(\sum_{i} u_{i}\right)-\Delta\left(\sum_{i} D_{i}\left(u_{i}\right)\right)=\sum_{i} f_{i} \leq 0
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\partial_{t} W-\Delta(A W) \leq 0, W=\sum_{i} u_{i}, A=\frac{\sum_{i} D_{i}\left(u_{i}\right)}{\sum_{i} u_{i}} .
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\end{gathered}
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## Three extensions of the $L^{2}$－estimate：$\left.(2): u_{0} \in L^{1}(\Omega)\right)$

－Recall：

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\partial_{t} W-\Delta(A W) \leq 0 \Rightarrow\|W\|_{L^{2}\left(Q_{T}\right)} \leq C\left\|W_{0}\right\|_{L^{2}(\Omega)}
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\|W\|_{L^{2}\left(Q_{T}, \tau\right)} \leq \frac{C(\underline{d}, \bar{d}, T)}{\tau^{N / 4}}\left\|W_{0}\right\|_{L^{1}(\Omega)} .
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- This allows to solve Systems of type (P)+(M) with quadratic reaction terms and with initial data in $L^{1}(\Omega)$ only.


## Three extensions of the $L^{2}$-estimate (3): A third one: $L^{2+\epsilon}$

(by J.A. Cañizo, L. Desvillettes, K. Fellner):

- There exists $\epsilon(N)>0$ such that

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- Allows global weak solutions for reaction terms growing faster than quadratic (growth depending on the dimension)
- Better results on asymptotic behaviors...


## Applications of the $L^{2}$-compactness to singular limits: (1)

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U_{1}+U_{2} \frac{1}{k_{1}} C \frac{k_{2}}{=} U_{3}+U_{4}
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\left\{\begin{array}{l}
\partial_{t} u_{1}-d_{1} \Delta u_{1}=-u_{1} u_{2}+k_{1} c \\
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$$

- The $L^{p}$-approach applies to this system so that global existence of classical solutions holds!


## Case of the O.D.E. system when $k_{1}+k_{2} \rightarrow+\infty$

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\left\{\begin{array}{l}
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－Quasi－steady state approximation：

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so that $c$ may be eliminated in the limit system ：

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$\partial_{t} u_{1}=-\alpha u_{1} u_{2}+(1-\alpha) u_{3} u_{4}$
with $\alpha=\lim _{k_{1}+k_{2} \rightarrow+\infty} \frac{k_{2}}{k_{1}+k_{2}}$.


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- The limit system may be obtained:

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The reaction

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U_{1}+U_{2} \frac{1}{\stackrel{\rightharpoonup}{k_{1}}} C \underset{\underset{1}{k_{2}}}{\stackrel{k_{2}}{1}} U_{3}+U_{4}
$$

'tends' to the limit dynamics

$$
U_{1}+U_{2} \underset{1}{\stackrel{\alpha}{\rightleftharpoons}} \alpha U_{3}+U_{4}
$$

+ convergence of the solutions of the corresponding systems.
Note the boundary layer at $t=0$ : the new initial values are $u_{1}^{0}+\alpha c^{0}, u_{2}^{0}+\alpha c^{0}, u_{3}^{0}+(1-\alpha) c^{0}, u_{4}^{0}+(1-\alpha) c^{0}$.


## $k_{1}+k_{2} \rightarrow+\infty$ for the full system?

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\left\{\begin{array}{l}
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\end{aligned}\right.
$$

- Again, formally the chemical reaction

$$
U_{1}+U_{2} \frac{1}{\underset{k_{1}}{\rightleftharpoons}} C \frac{k_{2}}{\underset{1}{1}} \quad U_{3}+U_{4}
$$

"tends" to the limit chemical reaction:

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$$

## The limit system

- Theorem. The solution $\left(u_{1}^{k}, u_{2}^{k}, c^{k}, u_{3}^{k}, u_{4}^{k}\right), k=\left(k_{1}, k_{2}\right)$ of the previous system converges as $k_{1}+k_{2} \rightarrow+\infty$ in $L^{2}\left(Q_{T}\right)^{5}$ for all $T>0$ to $\left(u_{1}, u_{2}, 0, u_{3}, u_{4}\right)$ solution of

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where $\alpha=\lim _{k_{1}+k_{2} \rightarrow \infty} \frac{k_{2}}{k_{1}+k_{2}}, \beta=1-\alpha$.

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- Remark: Boundary layer at $t=0$ : the new initial values are $u_{1}^{0}+\alpha c^{0}, u_{2}^{0}+\alpha c^{0}, u_{3}^{0}+(1-\alpha) c^{0}, u_{4}^{0}+(1-\alpha) c^{0}$.


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- M. Bisi, F. Conforto, L. Desvillettes-D. Bothe, M.P.


## Steps the proof of the $L^{2}$-convergence

$$
\left(S_{k}\right)\left\{\begin{array}{l}
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\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- $\partial_{t}\left(u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k}\right)-\Delta\left(d_{1} u_{1}^{k}+d_{2} u_{2}^{k}+2 d_{c} c^{k}+d_{3} u_{3}^{k}+d_{4} u_{4}^{k}\right)=0$, or, setting

$$
W^{k}=u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k},
$$

$$
\partial_{t} W^{k}-\Delta\left(A^{k} W^{k}\right)=0
$$

with: $\min d_{i} \leq A^{k} \leq 2 \max d_{i}$.

## Steps the proof of the $L^{2}$-convergence

$$
\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- $\partial_{t}\left(u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k}\right)-\Delta\left(d_{1} u_{1}^{k}+d_{2} u_{2}^{k}+2 d_{c} c^{k}+d_{3} u_{3}^{k}+d_{4} u_{4}^{k}\right)=0$, or, setting

$$
W^{k}=u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k},
$$

$$
\partial_{t} W^{k}-\Delta\left(A^{k} W^{k}\right)=0
$$

with: $\min d_{i} \leq A^{k} \leq 2 \max d_{i}$.

- This implies that $W^{k}$ is bounded in $L^{2}\left(Q_{T}\right)$ (for all $T$ ),


## Steps the proof of the $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- $\partial_{t}\left(u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k}\right)-\Delta\left(d_{1} u_{1}^{k}+d_{2} u_{2}^{k}+2 d_{c} c^{k}+d_{3} u_{3}^{k}+d_{4} u_{4}^{k}\right)=0$, or, setting

$$
\begin{aligned}
& W^{k}=u_{1}^{k}+u_{2}^{k}+2 c^{k}+u_{3}^{k}+u_{4}^{k} \\
& \qquad \partial_{t} W^{k}-\Delta\left(A^{k} W^{k}\right)=0
\end{aligned}
$$

$$
\text { with: } \min d_{i} \leq A^{k} \leq 2 \max d_{i}
$$

- This implies that $W^{k}$ is bounded in $L^{2}\left(Q_{T}\right)$ (for all $T$ ),
- and so are $u_{i}^{k}, c^{k}$.


## Steps of the proof of the strong $L^{2}$－convergence

$$
\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

－The nonlinearities $u_{1}^{k} u_{2}^{k}, u_{3}^{k} u_{4}^{k}$ are bounded in $L^{1}\left(Q_{T}\right), \forall T$ ， thanks to the $L^{2}$－estimate

## Steps of the proof of the strong $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The nonlinearities $u_{1}^{k} u_{2}^{k}, u_{3}^{k} u_{4}^{k}$ are bounded in $L^{1}\left(Q_{T}\right), \forall T$, thanks to the $L^{2}$-estimate
- Integrating the equation in $c^{k}$ gives

$$
\int_{\Omega} c^{k}(T)+\int_{Q_{T}}\left(k_{1}+k_{2}\right) c^{k}=\int_{\Omega} c^{0}+\int_{Q_{T}} u_{1}^{k} u_{2}^{k}+u_{3}^{k} u_{4}^{k} .
$$

## Steps of the proof of the strong $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The nonlinearities $u_{1}^{k} u_{2}^{k}, u_{3}^{k} u_{4}^{k}$ are bounded in $L^{1}\left(Q_{T}\right), \forall T$, thanks to the $L^{2}$-estimate
- Integrating the equation in $c^{k}$ gives

$$
\int_{\Omega} c^{k}(T)+\int_{Q_{T}}\left(k_{1}+k_{2}\right) c^{k}=\int_{\Omega} c^{0}+\int_{Q_{T}} u_{1}^{k} u_{2}^{k}+u_{3}^{k} u_{4}^{k}
$$

- All right-hand sides of the system are bounded in $L^{1}\left(Q_{T}\right)$ : this implies that the sequences $\left(u_{i}^{k}\right)_{k}$ are compact in $L^{1}\left(Q_{T}\right)$ and $c^{k} \rightarrow 0$ in $L^{1}\left(Q_{T}\right) \ldots$ But, this is not enough to pass to the limit !!


## Steps of the proof of the strong $L^{2}$-convergence

- Recall that, with $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$,

$$
\partial_{t} W^{k}-\Delta\left(A^{k} W^{k}\right)=0, \quad W^{k}(0)=W_{0}
$$

where

$$
\begin{aligned}
& 0<\underline{d} \leq A^{k} \leq \bar{d}<+\infty . \\
& W^{k} \rightarrow W:=\sum_{i} u_{i} \text { a.e. }
\end{aligned}
$$

## Steps of the proof of the strong $L^{2}$－convergence

－Recall that，with $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$ ，

$$
\partial_{t} W^{k}-\Delta\left(A^{k} W^{k}\right)=0, \quad W^{k}(0)=W_{0}
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where

$$
\begin{aligned}
& 0<\underline{d} \leq A^{k} \leq \bar{d}<+\infty \\
& W^{k} \rightarrow W:=\sum_{i} u_{i} \text { a.e. }
\end{aligned}
$$

－But，not only this implies the $L^{2}\left(Q_{T}\right)$－estimate on $W^{k}$ ，but it also implies the $L^{2}\left(Q_{T}\right)$－compactness of $W^{k}$ ．
（This is an extension of the previous compactness result to the case when $A^{k}$ is moving）．

## Last steps of the proof of $L^{2}$-convergence

$$
\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The sequence $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$ is compact in $L^{2}\left(Q_{T}\right)$.


## Last steps of the proof of $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
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\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The sequence $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$ is compact in $L^{2}\left(Q_{T}\right)$.
- Since, for all $i, u_{i}^{k} \leq W^{k}$, and, up to a subsequence, $u_{i}^{k}$ converges a.e., the $L^{2}\left(Q_{T}\right)$-compactness of $u_{i}^{k}$ follows.


## Last steps of the proof of $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
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\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
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\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The sequence $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$ is compact in $L^{2}\left(Q_{T}\right)$.
- Since, for all $i, u_{i}^{k} \leq W^{k}$, and, up to a subsequence, $u_{i}^{k}$ converges a.e., the $L^{2}\left(Q_{T}\right)$-compactness of $u_{i}^{k}$ follows.
- $c_{k} \rightarrow 0$ so that $\partial_{t} c^{k}-d_{c} \Delta c^{k} \rightarrow 0$, in the sense of distributions (only).


## Last steps of the proof of $L^{2}$-convergence

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\left(S_{k}\right)\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-u_{1}^{k} u_{2}^{k}+k_{1} c^{k} \\
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\partial_{t} c^{k}-d_{c} \Delta c^{k}=u_{1}^{k} u_{2}^{k}-\left(k_{1}+k_{2}\right) c^{k}+u_{3}^{k} u_{4}^{k} \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k} \\
\partial_{t} u_{4}^{k}-d_{4} \Delta u_{4}^{k}=-u_{3}^{k} u_{4}^{k}+k_{2} c^{k},
\end{array}\right.
$$

- The sequence $W^{k}=\sum_{i} u_{i}^{k}+2 c^{k}$ is compact in $L^{2}\left(Q_{T}\right)$.
- Since, for all $i, u_{i}^{k} \leq W^{k}$, and, up to a subsequence, $u_{i}^{k}$ converges a.e., the $L^{2}\left(Q_{T}\right)$-compactness of $u_{i}^{k}$ follows.
- $c_{k} \rightarrow 0$ so that $\partial_{t} c^{k}-d_{c} \Delta c^{k} \rightarrow 0$, in the sense of distributions (only).
- Same computations as for the O.D.E. to prove convergence toward the expected limit system. QED


## Applications of the $L^{2}$-estimate to singular limits: (2)

- (D. Bothe, MP, G. Rolland, '11)

$$
\left\{\begin{array}{l}
\partial_{t} u_{1}-d_{1} \Delta u_{1}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{2}-d_{2} \Delta u_{2}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{3}-d_{3} \Delta u_{3}=k\left[u_{1} u_{2}-u_{3}\right] \\
U_{1}+U_{2} \frac{k}{\bar{k}} U_{3}
\end{array}\right.
$$

For fixed $k$ : global existence of classical solutions $u^{k}$.

## Applications of the $L^{2}$－estimate to singular limits：（2）

－（D．Bothe，MP，G．Rolland，＇11）

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\partial_{t} u_{3}-d_{3} \Delta u_{3}=k\left[u_{1} u_{2}-u_{3}\right] \\
U_{1}+U_{2} \frac{k}{\bar{k}} U_{3}
\end{array}\right.
$$

For fixed $k$ ：global existence of classical solutions $u^{k}$ ．
－What is the limit kinetics when $k \rightarrow+\infty$ ？

## Applications of the $L^{2}$-estimate to singular limits: (2)

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\partial_{t} u_{2}-d_{2} \Delta u_{2}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{3}-d_{3} \Delta u_{3}=k\left[u_{1} u_{2}-u_{3}\right] \\
U_{1}+U_{2} \frac{k}{\hbar} U_{3}
\end{array}\right.
$$

For fixed $k$ : global existence of classical solutions $u^{k}$.

- What is the limit kinetics when $k \rightarrow+\infty$ ?
- Estimates independent of $k$ :

$$
\sup _{t}\left\|u_{i}^{k}(t)\right\|_{L^{1}(\Omega)} \leq C, \forall T>0,\left\|u_{i}^{k}\right\|_{L^{2}\left(Q_{T}\right)} \leq C
$$

## Applications of the $L^{2}$-estimate to singular limits: (2)

- (D. Bothe, MP, G. Rolland, '11)

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\partial_{t} u_{2}-d_{2} \Delta u_{2}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{3}-d_{3} \Delta u_{3}=k\left[u_{1} u_{2}-u_{3}\right] \\
U_{1}+U_{2} \frac{k}{\bar{k}} U_{3}
\end{array}\right.
$$

For fixed $k$ : global existence of classical solutions $u^{k}$.

- What is the limit kinetics when $k \rightarrow+\infty$ ?
- Estimates independent of $k$ :

$$
\sup _{t}\left\|u_{i}^{k}(t)\right\|_{L^{1}(\Omega)} \leq C, \forall T>0,\left\|u_{i}^{k}\right\|_{L^{2}\left(Q_{T}\right)} \leq C
$$

- A main difficulty: what about $k\left[u_{1} u_{2}-u_{3}\right]$ ?


## Case $d_{1}=d_{2}=d_{3}=d$

$\partial_{t}\left(u_{1}^{k}+u_{2}^{k}+2 u_{3}^{k}\right)-d \Delta\left(u_{1}^{k}+u_{2}^{k}+2 u_{3}^{k}\right)=0$
and by maximum principle

$$
\forall i, t,\left\|\left(u_{1}^{k}+u_{2}^{k}+2 u_{3}^{k}\right)(t)\right\|_{L^{\infty}(\Omega)} \leq\left\|u_{1}^{0}+u_{2}^{0}+2 u_{3}^{0}\right\|_{L^{\infty}(\Omega)} .
$$

Moreover, it may be proved (D. Bothe) that, as $k \rightarrow+\infty$

$$
\left\|k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]\right\|_{L^{1}\left(Q_{T}\right)} \leq C \text { independent of } k .
$$

Then, it follows that the $u_{i}^{k}$ converge, at least in any $L^{p}\left(Q_{T}\right)$, $p<+\infty$, to the unique regular nonnegative solution of

$$
\left\{\begin{array}{c}
\partial_{t}\left(u_{1}+u_{3}\right)-d \Delta\left(u_{1}+u_{3}\right)=0 \\
\partial_{t}\left(u_{2}+u_{3}\right)-d \Delta\left(u_{2}+u_{3}\right)=0
\end{array}\right\}+\text { boundary cond. }
$$

## Case of different diffusions $d_{1} \neq d_{2} \neq d_{3}$

$$
\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
$$

- A main difficulty: no a priori $L^{1}\left(Q_{T}\right)$-estimate on $k\left(u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right)$ seems to be true!


## Case of different diffusions $d_{1} \neq d_{2} \neq d_{3}$

$$
\left\{\begin{array}{c}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
$$

- On the other hand, for $i=1,2$, we have

$$
\left\{\begin{array}{l}
\partial_{t}\left(u_{i}^{k}+u_{3}^{k}\right)-\Delta\left[A_{1}^{k}\left(u_{i}^{k}+u_{3}^{k}\right)\right]=0 \\
0<\min \left\{d_{i}, d_{3}\right\} \leq A_{i}^{k}:=\frac{u_{i}^{k}+u_{3}^{k}}{d_{i} u_{i}^{k}+d_{3} u_{3}^{k}} \leq \max \left\{d_{i}, d_{3}\right\}<+\infty .
\end{array}\right.
$$

## Case of different diffusions $d_{1} \neq d_{2} \neq d_{3}$

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\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{u} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
$$

－On the other hand，for $i=1,2$ ，we have

$$
\left\{\begin{array}{l}
\partial_{t}\left(u_{i}^{k}+u_{3}^{k}\right)-\Delta\left[A_{1}^{k}\left(u_{i}^{k}+u_{3}^{k}\right)\right]=0 \\
0<\min \left\{d_{i}, d_{3}\right\} \leq A_{i}^{k}:=\frac{u_{i}^{k}+u_{3}^{k}}{d_{i} u_{i}^{k}+d_{3} u_{3}^{k}} \leq \max \left\{d_{i}, d_{3}\right\}<+\infty
\end{array}\right.
$$

－It follows that $u_{i}^{k}+u_{3}^{k}$ are bounded in $L^{2}\left(Q_{T}\right)$ for $i=1,2$ ．

## Case of different diffusions $d_{1} \neq d_{2} \neq d_{3}$

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\left\{\begin{array}{l}
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\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
$$

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\left\{\begin{array}{l}
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0<\min \left\{d_{i}, d_{3}\right\} \leq A_{i}^{k}:=\frac{u_{i}^{k}+u_{3}^{k}}{d_{i} u_{i}^{k}+d_{3} u_{3}^{k}} \leq \max \left\{d_{i}, d_{3}\right\}<+\infty
\end{array}\right.
$$

- It follows that $u_{i}^{k}+u_{3}^{k}$ are bounded in $L^{2}\left(Q_{T}\right)$ for $i=1,2$.
- If we knew that they converge pointwise, then we would deduce that they are compact in $L^{2}\left(Q_{T}\right)$ (previous result above).


## Case of different diffusions $d_{1} \neq d_{2} \neq d_{3}$

$$
\left\{\begin{array}{l}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
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\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
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$$
\left\{\begin{array}{l}
\partial_{t}\left(u_{i}^{k}+u_{3}^{k}\right)-\Delta\left[A_{1}^{k}\left(u_{i}^{k}+u_{3}^{k}\right)\right]=0 \\
0<\min \left\{d_{i}, d_{3}\right\} \leq A_{i}^{k}:=\frac{u_{i}^{k}+u_{3}^{k}}{d_{i} u_{i}^{k}+d_{3} u_{3}^{k}} \leq \max \left\{d_{i}, d_{3}\right\}<+\infty
\end{array}\right.
$$

- It follows that $u_{i}^{k}+u_{3}^{k}$ are bounded in $L^{2}\left(Q_{T}\right)$ for $i=1,2$.
- If we knew that they converge pointwise, then we would deduce that they are compact in $L^{2}\left(Q_{T}\right)$ (previous result above).
- Even not enough to conclude! Need to know that, separately, the $u_{i}^{k}$ are compact in $L^{2}\left(Q_{T}\right)$. Convergence a.e. of each of them would be enough (by dominated convergence).
- The missing information will be given by the entropy inequality


## The entropy inequality (we drop the $k$ )

$$
\left\{\begin{array}{c}
\partial_{t} u_{1}-d_{1} \Delta u_{1}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{2}-d_{2} \Delta u_{2}=-k\left[u_{1} u_{2}-u_{3}\right] \\
\partial_{t} u_{3}-d_{3} \Delta u_{3}=k\left[u_{1} u_{2}-u_{3}\right]
\end{array}\right.
$$

We set $\theta_{i}=u_{i} \log u_{i}-u_{i}$ and write the equation in $\theta_{i}$

$$
\begin{gathered}
\partial_{t} \theta_{i}=\log u_{i} \partial_{t} u_{i} ;-\Delta \theta_{i}+\frac{\left|\nabla u_{i}\right|^{2}}{u_{i}}=-\log u_{i} \Delta u_{i} \\
\partial_{t} \theta_{1}-d_{1} \Delta \theta_{1}+\frac{d_{1}\left|\nabla u_{1}\right|^{2}}{u_{1}}=-k\left[u_{1} u_{2}-u_{3}\right] \log u_{1} \\
\sum_{i}\left(\partial_{t}-d_{i} \Delta\right) \theta_{i}+\frac{d_{i}\left|\nabla u_{i}\right|^{2}}{u_{i}}=-k\left[u_{1} u_{2}-u_{3}\right]\left[\log \left(u_{1} u_{2}\right)-\log u_{3}\right] \leq 0
\end{gathered}
$$

- Integrating leads to the bound

$$
\int_{Q_{T}} \sum_{i} \frac{d_{i}\left|\nabla u_{i}\right|^{2}}{u_{i}}+k\left[u_{1} u_{2}-u_{3}\right]\left[\log \frac{u_{1} u_{2}}{u_{3}}\right] \leq C(\text { independent of } k)
$$

## Passing to the limit as $k \rightarrow \infty$

- Recall the estimates

$$
\begin{aligned}
& \sup _{t}\left\|u_{i}(t)\right\|_{L^{1}(\Omega)} \leq C, \forall T>0,\left\|u_{i}\right\|_{L^{2}\left(Q_{T}\right)} \leq C \\
& \int_{Q_{T}} \sum_{i} \frac{d_{i}\left|\nabla u_{i}\right|^{2}}{u_{i}}+k\left[u_{1} u_{2}-u_{3}\right]\left[\log \frac{u_{1} u_{2}}{u_{3}}\right] \leq C
\end{aligned}
$$

The last implies that each $\nabla \sqrt{u_{i}}$ is bounded in $L^{2}\left(Q_{T}\right)$.

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- Next, we use for $i=1,2$ the identity

$$
\partial_{t}\left(u_{i}+u_{3}\right)-\Delta\left(d_{i} u_{i}+d_{3} u_{3}\right)=0
$$

to show that $\partial_{t} \sqrt{u_{i}+u_{3}} \in L^{2}\left(0, T ; H^{-1}(\Omega)\right)+L^{1}\left(Q_{T}\right)$
By Aubin-Simon type of compactness, we deduce that $u_{i}+u_{3}$ is compact in $L^{1}\left(Q_{T}\right)$ and therefore converges a.e. ...which implies they converge in $L^{2}\left(Q_{T}\right)$ thanks to our previous analysis.

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- We use the pointwise entropy inequality to prove that all three $u_{i}$ converge a.e.. Whence their convergence in $L^{2}\left(Q_{T}\right)$.


## A general convergence result

(D. Bothe, M.P., G. Rolland)

$$
\left\{\begin{array}{c}
\partial_{t} u_{1}^{k}-d_{1} \Delta u_{1}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{2}^{k}-d_{2} \Delta u_{2}^{k}=-k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right] \\
\partial_{t} u_{3}^{k}-d_{3} \Delta u_{3}^{k}=k\left[u_{1}^{k} u_{2}^{k}-u_{3}^{k}\right]
\end{array}\right.
$$

Theorem. Up to a subsequence, the $u_{i}^{k}$ converge in $L^{2}\left(Q_{T}\right), \forall T>0$ to a weak nonnegative solution of
$(\operatorname{Lim})\left\{\begin{array}{c}\partial_{t}\left(u_{1}+u_{3}\right)-\Delta\left(d_{1} u_{1}+d_{3} u_{3}\right)=0 \\ \partial_{t}\left(u_{2}+u_{3}\right)-\Delta\left(d_{2} u_{2}+d_{3} u_{3}\right)=0 \\ u_{1} u_{2}=u_{3} . \\ \left(u_{1}+u_{3}\right)(0)=u_{1}^{0}+u_{3}^{0},\left(u_{2}+u_{3}\right)(0)=u_{2}^{0}+u_{3}^{0},\end{array}\right.$

## About the problem (Lim)

$(\operatorname{Lim})\left\{\begin{array}{c}\partial_{t}\left(u_{1}+u_{3}\right)-\Delta\left(d_{1} u_{1}+d_{3} u_{3}\right)=0 \\ \partial_{t}\left(u_{2}+u_{3}\right)-\Delta\left(d_{2} u_{2}+d_{3} u_{3}\right)=0 \\ u_{1} u_{2}=u_{3} . \\ \left(u_{1}+u_{3}\right)(0)=u_{1}^{0}+u_{3}^{0},\left(u_{2}+u_{3}\right)(0)=u_{2}^{0}+u_{3}^{0},\end{array}\right.$
If we set, $w_{1}:=u_{1}+u_{3}, w_{2}=u_{2}+u_{3}$, then it is equivalent to the $2 \times 2$ cross-diffusion system
$\left(\operatorname{Lim}^{\prime}\right)\left\{\begin{array}{c}\partial_{t} w_{1}-\Delta \psi_{1}\left(w_{1}, w_{2}\right)=0 \\ \partial_{t} w_{2}-\Delta \psi_{2}\left(w_{1}, w_{2}\right)=0 \\ w_{1}(0)=u_{1}^{0}+u_{3}^{0}, w_{2}(0)=u_{2}^{0}+u_{3}^{0},\end{array}\right.$
where $\psi=\left(\psi_{1}, \psi_{2}\right):\left[0, \infty\left[^{2} \rightarrow \boldsymbol{R}^{2}\right.\right.$ is $\boldsymbol{C}^{\infty}$ and the Jacobian matrix $D \psi\left(w_{1}, w_{2}\right)$ satisfies the spectral conditions for this problem to have unique local classical solution (see H. Amann's theory).

## Open problems

As a by-product of the existence of the limit on $[0, \infty)$ of the $k$-systems, we obtain existence of a global weak solution, but (1) Does it coincide with the (a priori local) classical solution? We can prove uniqueness of global weak solutions for some range of the diffusions $\left[\left(d_{1}-d_{3}\right)^{2}\left(d_{2}-d_{3}\right)^{2}<16 d_{1} d_{2} d_{3}^{2}\right]$. In this case, the answer is yes, but
(2) It may a priori happen that the strong solution becomes (only) weak after some time.
(3) Does one have uniqueness of weak solutions for all values of the $d_{i}$ 's?

## Applications of the $L^{2}$-compactness to some "relaxed"

 cross-diffusion systems: (3)Classical conservative cross-diffusion systems may be written

$$
\left\{\begin{array}{l}
\partial_{t} u_{i}-\Delta\left[a_{i}(u) u_{i}\right]=0, i=1, \ldots, m \\
\partial_{\nu}\left(a_{i}(u) u_{i}\right)=0, u_{i}(0)=u_{i}^{0} \geq 0
\end{array}\right.
$$

where, for instance,

$$
a_{i}(u)=d_{i}+\sum_{j} d_{i j} u_{j}^{p}
$$

[N. Shigesada, K. Kawasaki and E. Teramoto]. Local existence of strong solutions by Amann's theory, but not much about global existence except for $p=1$ (see results and survey by A. Jüngel).

Interaction between species through motion, not through reaction $\rightarrow \rightarrow$ Formation of "patterns like in Turing's instabilities"

Applications of the $L^{2}$-compactness to some "relaxed" cross-diffusion systems: (3)

- Existence of solutions to the cross-diffusion system where $a_{i}:(0, \infty)^{m} \rightarrow[\underline{d}, \infty)$ continuous (only), $\underline{d}>0$ :

$$
\left\{\begin{array}{l}
\partial_{t} u_{i}-\Delta\left[a_{i}(\tilde{u}) u_{i}\right]=0, \quad i=1, \ldots, l \\
\tilde{u}_{i}-\delta_{i} \Delta \tilde{u}_{i}=u_{i}, \quad \delta_{i}>0 \\
\partial_{\nu} u_{i}=\partial_{\nu} \tilde{u}_{i}=0, u_{i}(0)=u_{i}^{0} \geq 0
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$$

Model proposed by M. Bendahmane, Th. Lepoutre, A. Marrocco, B. Perthame (partial results in dimensions $N=1,2$ ).

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- This relaxed version takes into account that the intensity of the underlying brownian depends on the density of the whole population in a neighborhood of size $\delta_{i}$ of each point.


## A general global existence result

THEOREM. (Th. Lepoutre, MP, G. Rolland, '11 ): Existence of global solutions satisfying for all $T>0, p<\infty$

$$
\begin{gathered}
u_{i} \in L^{p}\left(Q_{T}\right), \tilde{u}_{i} \in C^{\alpha}\left(Q_{T}\right) \cap L^{p}\left(0, T ; W^{2, p}\left(Q_{T}\right)\right), \\
u_{i}(t)-\Delta\left[\int_{0}^{t} a_{i}(\tilde{u}) u_{i}\right]=u_{i}^{0} . \\
\tilde{u}_{i}-\delta_{i} \Delta \tilde{u}_{i}=u_{i}
\end{gathered}
$$

If, moreover, $a_{i}$ is locally Lipschitz continuous, the solution is classical, unique and

$$
\begin{gathered}
u_{i} \in L^{\infty}\left(Q_{T}\right), \partial_{t} u_{i}, \Delta\left(a_{i}(\tilde{u}) u_{i}\right) \in L_{l o c}^{p}\left((0, T] ; L^{p}(\Omega)\right) . \\
\partial_{t} u_{i}-\Delta\left(a_{i}\left(\tilde{u}_{i}\right) u_{i}\right)=0 .
\end{gathered}
$$

## Step 1 of the proof：$L^{2}$－estimate

－We first truncate the nonlinearities $a_{i}(\cdot)$ and prove existence of a fixed point for the mapping

$$
\begin{aligned}
& \mathcal{T}: v=\left(v_{i}\right)_{1 \leq i \leq m} \rightarrow u=\left(u_{i}\right)_{1 \leq i \leq m} \in X==\Pi_{i=1}^{m} X_{i}, \\
& u_{i} \text { weak solution of } \partial_{t} u_{i}-\Delta\left(a_{i}(\tilde{v}) u_{i}\right)=0, u_{i}(0)=u_{i}^{0} \\
& X_{i}=\left\{v_{i} \in L^{2}\left(Q_{T}\right) ; \partial_{t} \tilde{v}_{i} \in L^{2}\left(Q_{T}\right), \tilde{v}_{i}=\left(I-\delta_{i} \Delta\right)^{-1} v_{i}\right\}
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- We use the $L^{2}$ estimate + compactness to prove that this mapping $\mathcal{T}$ is well-defined + satisfies the Leray-Schauder fixed-point theorem:


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- First, we can solve in $L^{2}\left(Q_{T}\right)$-with estimates- the linear problem

$$
u_{i}(t)-\Delta \int_{0}^{t} A_{i} u_{i}=u_{i}^{0}, \partial_{\nu} u_{i}=0,(*)
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where $A_{i} \in L^{\infty}\left(Q_{T}\right), 0<\underline{a} \leq A_{i} \leq \bar{a}<\infty$. Here $A_{i}:=a_{i}(\tilde{v})$.

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- Next, the $L^{2}$ compactness together with the choice of $X_{i}$ implies that $\mathcal{T}$ is compact. Coupled with uniqueness of the weak solutions of $\left({ }^{*}\right)$, it follows that $\mathcal{T}$ is continuous.


## Step 2 of the proof: $\tilde{u} \in L^{\infty}$ !

$$
u_{i}(t)-\Delta \int_{0}^{t} a_{i}(\tilde{u}) u_{i}=u_{i}^{0}, \tilde{u}_{i}(t)-\delta_{i} \Delta \tilde{u}_{i}(t)=u_{i}(t)
$$

may be rewritten

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\tilde{u}_{i}(t)-\Delta\left[\delta_{i} \tilde{u}_{i}+\int_{0}^{t} a_{i}(\tilde{u}) u_{i}\right]=u_{i}^{0}
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- Since $\tilde{u}_{i} \geq 0$, and thanks to Neumann bdy conditions:

$$
\left\|\delta_{i} \tilde{u}_{i}+\int_{0}^{t} a_{i}(\tilde{u}) u_{i}\right\|_{L^{\infty}(\Omega)} \leq C\left[\left\|u_{i}^{0}\right\|_{L \infty(\Omega)}+\int_{\Omega}\left\{\delta_{i} \tilde{u}_{i}+\int_{0}^{t} a_{i}(\tilde{u}) u_{i}\right\}\right] .
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$$

- We may bound $\int_{Q_{T}} a_{i}(\tilde{u}) u_{i}$ independently of the upper bound of $a_{i}$ (main point!)
- It follows $\left\|\tilde{u}_{i}\right\|_{L^{\infty}\left(Q_{T}\right)} \leq C$. Thus, we get rid of the truncation of $a_{i}$.


## Step 3: Use of Krylov-Safonov estimates

- We apply the $C^{\alpha}$ estimates of Krylov-Safonov to $U_{i}=\int_{0}^{t} a_{i}(\tilde{u}) u_{i}$ which satisfies

$$
\partial_{t} U_{i}-a_{i}(\tilde{u}) \Delta U_{i}=a_{i}(\tilde{u}) u_{i}^{0} \in L^{\infty}\left(Q_{T}\right),
$$

where now $\underline{a} \leq a_{i}(\tilde{u}) \leq \bar{a}(T)<+\infty$.

$$
\Rightarrow\left\|U_{i}\right\|_{C^{\alpha}\left(Q_{T}\right)} \leq C \text { for some } \alpha \in(0,1)
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$$
\begin{gathered}
-\Delta w_{i}=u_{i}^{0}-\tilde{u}_{i} \in L^{\infty}\left(Q_{T}\right) \Rightarrow \nabla w_{i} \in L^{\infty}\left(Q_{T}\right) \\
\partial_{t} w_{i}-\delta_{i} \Delta\left(\partial_{t} w_{i}\right)=a_{i}(\tilde{u}) u_{i} \leq C(T) u_{i} \\
\Rightarrow 0 \leq \partial_{t} w_{i} \leq C_{1}(T) \tilde{u}_{i} \Rightarrow \partial_{t} w_{i} \in L^{\infty}\left(Q_{T}\right)
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\Rightarrow 0 \leq \partial_{t} w_{i} \leq C_{1}(T) \tilde{u}_{i} \Rightarrow \partial_{t} w_{i} \in L^{\infty}\left(Q_{T}\right)
\end{gathered}
$$

- $\Rightarrow w_{i}$ is Lipschitz-continuous

$$
\Rightarrow\left\|\delta_{i} \tilde{u}_{i}\right\|_{C^{\alpha}\left(Q_{T}\right)} \leq C
$$

## Step 4: Use the maximal $L^{p}$-regularity theory

- Recall that for $U_{i}(t)=\int_{0}^{t} a_{i}(\tilde{u}) u_{i}$

$$
\partial_{t} U_{i}-a_{i}(\tilde{u}) \Delta U_{i}=a_{i}(\tilde{u}) u_{i}^{0} \in L^{\infty}\left(Q_{T}\right),
$$

Now, we know that $a_{i}(\tilde{u})$ is continuous on $Q_{T}$ and bounded from below. Therefore, we have $L^{P}$-maximal regularity. In particular,

$$
\begin{gathered}
\partial_{t} U_{i}=a_{i}(\tilde{u}) u_{i} \in L^{p}\left(Q_{T}\right) \text { for all } p<+\infty . \\
\Rightarrow u_{i} \in L^{p}\left(Q_{T}\right)
\end{gathered}
$$

## Step 4: Use the maximal $L^{p}$-regularity theory

- Recall that for $U_{i}(t)=\int_{0}^{t} a_{i}(\tilde{u}) u_{i}$

$$
\partial_{t} U_{i}-a_{i}(\tilde{u}) \Delta U_{i}=a_{i}(\tilde{u}) u_{i}^{0} \in L^{\infty}\left(Q_{T}\right),
$$

Now, we know that $a_{i}(\tilde{u})$ is continuous on $\bar{Q}_{T}$ and bounded from below. Therefore, we have $L^{P}$-maximal regularity. In particular,

$$
\begin{gathered}
\partial_{t} U_{i}=a_{i}(\tilde{u}) u_{i} \in L^{p}\left(Q_{T}\right) \text { for all } p<+\infty . \\
\Rightarrow u_{i} \in L^{p}\left(Q_{T}\right)
\end{gathered}
$$

- And we get more if $a_{i}$ is locally Lipschitz :

$$
\partial_{t} u_{i}, \Delta\left(a_{i}(\tilde{u}) u_{i}\right) \in L_{l o c}^{p}\left((0, T] ; L^{p}(\Omega)\right), \forall p<\infty .
$$

## Again the $L^{2}$-approach for uniqueness!

Let $u, v$ be two solutions, $a_{i}=a_{i}(\tilde{u}), b_{i}=a_{i}(\tilde{v})$.

$$
\partial_{t}\left(u_{i}-v_{i}\right)-\Delta\left[a_{i}\left(u_{i}-v_{i}\right)+v_{i}\left(a_{i}-b_{i}\right)\right]=0 .
$$

This may be rewritten with $U_{i}=u_{i}-v_{i}, \tilde{U}=\tilde{u}-\tilde{v}$

$$
\begin{gathered}
\partial_{t} U_{i}-\Delta\left[a_{i} U_{i}+v_{i} A_{i} \cdot \tilde{U}\right]=0, i=1, \ldots, m, \\
A_{i}=\int_{0}^{1} D a_{i}(t \tilde{u}+(1-t) \tilde{v}) d t \in L^{\infty}\left(Q_{T}\right) .
\end{gathered}
$$

Proving $U \equiv 0$ is equivalent to solving the dual problem for any $F \in C_{0}^{\infty}\left(Q_{T}\right)^{m}$ (here $\left.B_{i j}=v_{j} A_{j i}\right)$ :

$$
\left\{\begin{array}{l}
\psi_{i}, \partial_{t} \psi_{i}, \Delta \psi_{i} \in L^{2}\left(Q_{T}\right)  \tag{3}\\
\partial_{t} \psi_{i}+a_{i} \Delta \psi_{i}+\left(I-\delta_{i} \Delta\right)^{-1}\left(B_{i} \cdot \Delta \psi\right)=F_{i} \\
\psi=\left(\psi_{1}, \ldots, \psi_{m}\right), \partial_{\nu} \psi_{i}=0, \psi_{i}(T)=0 .
\end{array}\right.
$$

